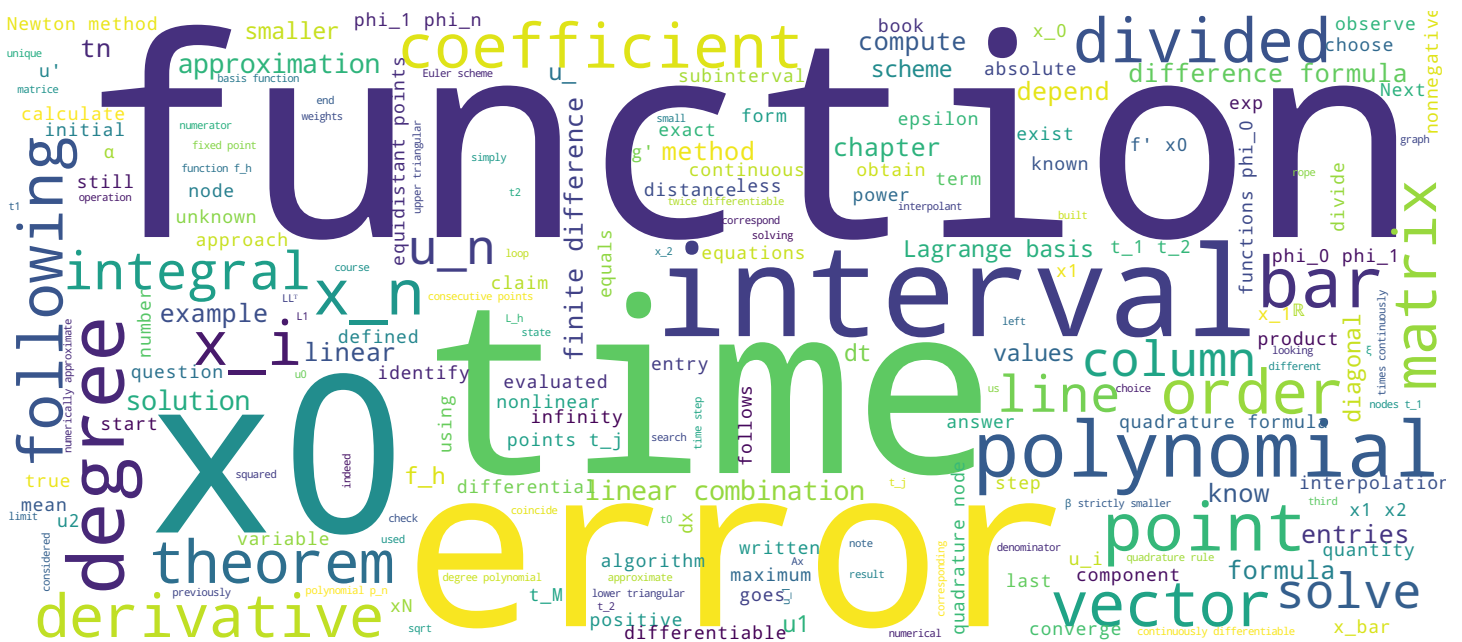


Résumé

Introduction à l'analyse numérique

Prof. Marco Picasso



Résumé Chap 1 interpolation



- $p \in \mathbb{P}_n$ tq $p(t_j) = p_j \quad j=0,1,\dots,n$

$$p(t) = \sum_{j=0}^n p_j \varphi_j(t)$$

$\varphi_0 \varphi_1 \varphi_2 \dots \varphi_n$ base de Lagr. de \mathbb{P}_n ass. aux pts t_0, t_1, \dots, t_n

$$\varphi_k(t) = \prod_{\substack{j=0 \\ j \neq k}}^n \frac{t - t_j}{t_k - t_j}$$

- $f: [a,b] \rightarrow \mathbb{R}$

$$p_n(t) = \sum_{j=0}^n f(t_j) \varphi_j(t)$$

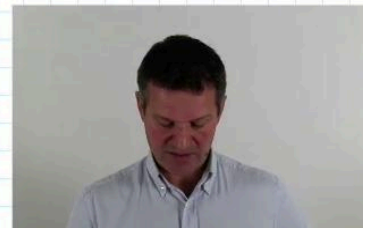
t_j equidist $t_j = a + \frac{b-a}{n} j \quad j=0,1,\dots,n$

$p_n \xrightarrow{n \rightarrow \infty} f$? dépend de f

- interpol. intervalles $f: [a,b] \rightarrow \mathbb{R} \quad f_n \in \mathcal{C}^0[a,b]$

degré 1 $|f - f_n| = O(h^2)$

— 2 $|f - f_n| = O(h^3)$



A short summary of this first chapter on interpolation. The problem we tried to solve was the following: we search for a polynomial of degree n such that $p(t_j) = p_j$. The values t_j and p_j are given for all indexes $j = 0, 1, \dots, n$. The solution to the problem can be written as a linear combination of the functions $\varphi_0, \varphi_1, \dots, \varphi_n$ which form the Lagrange basis of polynomials of degree n and depend on the choice of points t_0, t_1, \dots, t_n . Hence the solution is a linear combination of these functions $\varphi_0, \varphi_1, \dots, \varphi_n$, and the coefficients of the linear combination are the values given by the p_j . So we have $p(t)$ equal to the sum over $j = 0, \dots, n$ of the product of p_j times $\varphi_j(t)$. The k -th basis function of the Lagrange basis is a polynomial of degree n which must cancel out for all points, except for j equal to k . The numerator is monomials of the form $(t - t_j)$, and the denominator is composed of monomials $(t_k - t_j)$ such that $\varphi_k(t_k)$ is equal to 1. That must be understood for the exam. Next we considered a function f defined on a continuous interval $[a,b]$. We built the polynomial of degree n which coincides with the function f in a given number of points t_j equidistant on the interval $[a,b]$.

Notes

Summary



Résumé Chap 1 interpolation

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$p_n \xrightarrow{n \rightarrow \infty} f$? dépend de f

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degré 1 $|f - f_h| = O(h^2)$

— 2 $|f - f_h| = O(h^3)$

Again, we have p_n a linear combination of these fixed functions, the functions forming the Lagrange basis. The coefficients of the linear combination are the values of the function f evaluated at points t_j . As n approaches infinity, we want to know if the polynomial p_n approaches the function f ? The answer is given by a theorem which depends on the derivative of order $n+1$ of the function f . We have considered another problem : interpolation by intervals. We built f_h , the interpolant by interval of the function f , with equidistant points. h is the distance between two consecutive points which will approach zero. So f_h is a function which is continuous, but not differentiable. This function coincides with the function f at these equidistant points and the function f_h is a polynomial of degree 1 on each subinterval. In this case the error between f and f_h is an error which follows h^2 , this is true only if f is twice differentiable. Now if you consider an interpolant f_h of degree 2 on each subinterval, well you get that the distance between f and f_h is of order h^3 , so the error is divided by $2^3 = 8$ every time h is divided by two.

Notes

Summary

