

Chap 5: Decomposition LL^T - Example



Chap 5: Décomposition LL^T - Exemple

$$\begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{pmatrix} = \begin{pmatrix} l_1 & & & \\ m_1 & l_2 & & \\ & m_2 & \ddots & \\ & & m_{N-1} & l_N \end{pmatrix} \begin{pmatrix} l_1 & m_1 & & \\ & l_2 & m_2 & \\ & & \ddots & m_{N-1} \\ & & & l_N \end{pmatrix}$$

$A = L L^T$

$$\forall \vec{x} \in \mathbb{R}^N \quad \vec{x}^T A \vec{x} = (x_1 \ x_2 \ \dots \ x_N) \begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix}$$

Let's study the decomposition LL^T with the example of a tridiagonal matrix. So the matrix A is the tridiagonal matrix with 2's on the main diagonal, -1 on the diagonal subdiagonal and -1 on the diagonal superdiagonal. We will first show that this matrix A is symmetric and positive definite, we know that there is a decomposition LL^T , where L is a lower triangular matrix, and consequently L^T is an upper matrix, moreover, the coefficients on the diagonal of L are strictly positive. I will note those entries L_1, L_2 , until L_N and so for L^T I will also have L_1, L_2, \dots, L_N . The matrix L is lower triangular, so there are 0's in the upper triangular part, and so here 0's on the lower triangular part of L^T . Actually, the lower part of L reduces to a subdiagonal. The subdiagonal of L has coefficients m_1, m_2 , until $m(N-1)$ and so L^T is reduced to a superdiagonal m_1, m_2 , until $m(N-1)$. Here is $L(N-1)$. First of all, let's show that this matrix A is indeed symmetric positive definite. We take any x in \mathbb{R}^N and compute $x^T A x$, So x^T is the vector with entries x_1, x_2 , until x_N , laying down. We have the matrix A , with 2 on the diagonal, -1 on the subdiagonal, -1 on the superdiagonal, and the vector x , x_1, x_2, \dots, x_N .

Notes

Summary



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$$A = \begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{pmatrix} = \begin{pmatrix} l_1 & & & \\ m_1 & l_2 & & \\ & m_2 & l_3 & \\ & & m_{N-1} & l_N \end{pmatrix} \begin{pmatrix} 1 & m_1 & m_2 & \dots & m_{N-1} \\ & 1 & & & \\ & & 1 & & \\ & & & \ddots & \\ & & & & 1 \end{pmatrix}$$

$A \qquad L \qquad L^T$

$$\forall \vec{x} \in \mathbb{R}^N \quad \vec{x}^T A \vec{x} = (x_1 \ x_2 \ \dots \ x_N) \begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & -1 & 2 & -1 \\ & & -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} = 2x_1^2 - 2x_1x_2 + 2x_2^2 - 2x_2x_3 + \dots - 2x_{N-1}x_N + 2x_N^2$$

$$= x_1^2 + (x_1^2 - 2x_1x_2 + x_2^2) + (x_2^2 - 2x_2x_3 + x_3^2) + \dots + (x_{N-1}^2 - 2x_{N-1}x_N + x_N^2) + x_N^2$$

$$= x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + \dots + (x_{N-1} - x_N)^2 + x_N^2$$

If I do the computation of $\vec{x}^T A \vec{x}$ I obtain $2x_1^2$ plus $2x_2^2$ donc il y a $2x_1^2$, then, here I have $-x_1x_2$, donc j'ai $-x_1x_2$, et en fait, j'ai $-2x_1x_2 + 2x_2^2$, $-2x_2x_3 + 2x_3^2$, until the end, where there is $-2x_{N-1}x_N + 2x_N^2$. I'd like to show that $\vec{x}^T A \vec{x}$ is nonnegative, so a possibility is to make squares appear, $2x_1^2$ is $x_1^2 + x_1^2$, We have the double product $-2x_1x_2$, and I have x_2^2 , so I can keep this term, I observe a square, then I'll have $x_2^2 - 2x_1x_2 + x_1^2$, and so on until the last term which will be here $x_{N-1}^2 - 2x_{N-1}x_N + x_N^2$, and again x_N^2 . So observe now that squares appear, $x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + \dots + (x_{N-1} - x_N)^2 + x_N^2$. So $\vec{x}^T A \vec{x}$ is indeed a sum of squares, so this term is nonnegative. Moreover, $\vec{x}^T A \vec{x} = 0$ if and only if all those terms are 0, since they are squares. So I'll have $x_1 = 0$, if $x_1 = 0$ I'll get $x_2 = 0$, and so on until I get $x_N = 0$. Obviously this matrix is symmetric, so I've shown that this matrix A is sdp. Let's move to the Cholesky decomposition algorithm. I told you that we have to identify the coefficients of A and LL^T in the right order, so I will start with the first column.

Notes

Summary



Chap 5 : Décomposition LL^T - Exemple

$$A = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} l_1 & 0 \\ m_1 & l_2 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} l_1 & m_1 \\ 0 & l_2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$A \qquad L \qquad L^T$

$$\forall \vec{x} \in \mathbb{R}^N \quad \vec{x}^T A \vec{x} = (x_1 \ x_2 \ \dots \ x_N) \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} = 2x_1^2 - 2x_1x_2 + 2x_2^2 - 2x_2x_3 + \dots - 2x_{N-1}x_N + 2x_N^2$$

$$= x_1^2 + (x_1^2 - 2x_1x_2 + x_2^2) + (x_2^2 - 2x_2x_3 + x_3^2) + \dots + (x_{N-1}^2 - 2x_{N-1}x_N + x_N^2) + x_N^2$$

$$= x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + \dots + (x_{N-1} - x_N)^2 + x_N^2$$

$$\begin{aligned} 2 &= l_1^2 \rightarrow l_1 = \sqrt{2} \\ -1 &= m_1 l_1 \rightarrow m_1 = -1/l_1 \\ 2 &= m_1^2 + l_2^2 \rightarrow l_2 = \sqrt{2 - m_1^2} \end{aligned}$$

Algo : \vec{l}, \vec{m}
 $l_1 = \sqrt{2}$
 Faire $i = 1, N-1$
 $m_i = -1/l_i$

The entries of the first column of A will give me the coefficients of the first column of L , indeed the coefficient 2 here is the entry 1,1 of the matrix A , I must do the inner product between the first line and the first column, so I get $2 = L_1^2$, so $L_1 = \sqrt{2}$. I continue, I get the coefficients of the second line and first column, -1 equals the second line times the first column, $m_1 \cdot L_1$. I get $m_1 = -1/L_1$. And so on I identify the coefficients here of the second column of A , with the coefficients of the second column of the product LL^T , and I'll get the coefficients of the second column of L . I continue, I have 2, the entry 2,2 of the matrix A which equals the inner product of this line with this column, which is $m_1^2 + L_2^2$, I get $L_2 = \sqrt{2 - m_1^2}$, and so on. Now I can write the LL^T decomposition algorithm. « Algorithm » This algorithm uses the vector L , the vector of entries L_1, L_2, \dots, L_N , the vector m , which is the vector with entries m_1, m_2 until $m(N-1)$. et le vecteur \vec{u} , qui est -- et c'est tout (\vec{u} barré). So I initialize the algorithm, the initialization is $L_1 = \sqrt{2}$, and then I do a loop for i from 1 to $N-1$, From L_1 , I will compute m_1 , from L_i I will compute m_i , which equals $-1/L_i$.

Notes

Summary



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$$A = \begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & & \ddots & \ddots \\ & & & 2 & -1 \\ & & & -1 & 2 \end{pmatrix} = \begin{pmatrix} l_1 & & & \\ m_1 & l_2 & & \\ & m_2 & \ddots & \\ & & & m_{N-1} & l_N \end{pmatrix} \begin{pmatrix} 1 & m_1 & & \\ & 1 & m_2 & \\ & & \ddots & m_{N-1} \\ & & & 1 \end{pmatrix}$$

$A \qquad L \qquad L^T$

$$\forall \vec{x} \in \mathbb{R}^N \quad \vec{x}^T A \vec{x} = (x_1 \ x_2 \ \dots \ x_N) \begin{pmatrix} 2 & -1 & & \\ -1 & 2 & -1 & \\ & & \ddots & \ddots \\ & & & 2 & -1 \\ & & & -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{pmatrix} = 2x_1^2 - 2x_1x_2 + 2x_2^2 - 2x_2x_3 + \dots - 2x_{N-1}x_N + 2x_N^2$$

$$= x_1^2 + (x_1^2 - 2x_1x_2 + x_2^2) + (x_2^2 - 2x_2x_3 + x_3^2) + \dots + (x_{N-1}^2 - 2x_{N-1}x_N + x_N^2) + x_N^2$$

$$= x_1^2 + (x_1 - x_2)^2 + (x_2 - x_3)^2 + \dots + (x_{N-1} - x_N)^2 + x_N^2$$

$$\begin{aligned} 2 &= l_1^2 \rightarrow l_1 = \sqrt{2} \\ -1 &= m_1 l_1 \rightarrow m_1 = -1/l_1 \\ 2 &= m_1^2 + l_2^2 \rightarrow l_2 = \sqrt{2 - m_1^2} \end{aligned}$$

Algo : \vec{l}, \vec{m}

$$l_1 = \sqrt{2}$$

Faire $i = 1, N-1$

$$m_i = -1/l_i$$

$$l_{i+1} = \sqrt{2 - m_i^2}$$

Division par zéro, racine carrée nbre négatif?

Non

Nombre d'opération $O(N)$

Then I am able to compute $l(i+1)$ which equals $\sqrt{2 - m_i^2}$. That is our algorithm, as previously, we can check several things. The first one is: is there is division by 0 or a negative square root? - the square root of a negative number. The answer is no. Why? Since the matrix is sdp, it is regular, and what I did not mention is, that if this this matrix is symmetric positive definite, then all the principal submatrix are also regular. Finally if you get the square root of a negative number, then by contraposition, then the matrix A isn't symmetric positive definite. So there are no divisions by 0 and no square root of negative numbers. The number of operations is still $O(N)$, which means it's doubled each time we double N, simply because there is only one loop from 1 to N.

Notes

Summary

